

## **Topic Notes: Subprograms**

Our next familiar programming language construct to examine in more detail is the *subprogram*. Whether called subroutines, procedures, functions, or methods, many of the fundamentals are the same.

We typically categorize subprograms into these groups:

- procedures or subroutines that do not return a value
- functions that return a single value
- *methods* are associated with an object (see Chapters 11-12, which we will likely only touch on briefly)

Even in early programming languages, the use of subprograms was emphasized to promote

- code reusability
- modularity a high-level problem decomposition
- resource efficiency
  - memory space for code
  - reduce programming time

The general behavior of subprograms is well known to us as programmers:

- a subprogram has a single entry point (the beginning)
- the caller's execution stops while the subprogram executes
- control returns to the caller upon completion

And the basic terminology:

- subprogram *definition* the declaration and implementation of a subprogram
- subprogram *call* the explicit activation statement of a subprogram

- subprogram *header* the first part of the definition
  - ssometimes called a *specification* or *interface*
  - specifies type of subprogram, its name, and its parameters (if any)
- subprogram *body* statements which implement the subprogram
- subprogram *parameter profile* or *signature* the number, order and types of the subprogram's formal parameters
- subprogram *protocol* a subprogram's parameter profile plus its return type
- subprogram *declaration* a mini "pre-definition", stating protocol information (*e.g.*, C/C++ Prototypes)
- *formal parameter* name listed in the subprogram header and used in the subprogram like a local variable
- actual parameter a value or address used in the subprogram call statement

How do actual parameters get matched to the appropriate formal parameters on a subprogram call?

We are likely most familiar with *positional parameters* – the mapping of actual to formal parameters is based on the order in the parameter list:

```
int sub(int x, int y) {
  return x - y;
}
...
sub(5, 2);
```

Here, we all know that x is assigned 5 and y is assigned 2 on the example function call.

You may or may not have seen examples of languages that use *keyword parameters*, where the actual parameters are explicitly matched to formal parameters by name.

This means parameters can be listed in any order, avoiding transposition errors. However, it requires that callers must know the formal parameter names.

Ada (of course) is one of the languages that supports this. The text shows an example from Python.

Fortran 90 does this as well:

```
On the web: F90 Keyword arguments and default arguments at http://aeneas.ps.uci.edu/absoft/c8.htm
```

The above also shows how Fortran 90 deals with *default parameters*. In these cases, a parameter can be left off and given a default value when it is not specified.

C++ supports this, but since its parameters are specified only positionally, any optional parameters must come at the end of the parameter list.

#### **See Example:**

/home/cs433/examples/cppdefault

Many languages also support variable-length argument lists (*variadic functions*). We know that C must support this if functions like printf could work, since it can take any number of parameters, depending on the number of specifiers in the format string.

But how does it do it?

### **See Example:**

/home/cs433/examples/varargs

For examples in many languages:

On the web: Wikipedia article "Variadic function" at

http://en.wikipedia.org/wiki/Variadic\_function

Perl passes all parameters to subprograms in a special "parameter array" called @\_\_.

On the web: Using the Parameter Array at

http://www.cs.cf.ac.uk/Dave/PERL/node50.html

## **Models of Parameter Passing**

The text discusses many design issues for subprograms, but we will focus on just a few.

The first is the semantics of parameter passing. That is, when we have a subprogram, how does information pass through the parameters between the caller and the callee?

There are three major models:

- in mode information flows through the parameter from caller to callee
- out mode information flows through the parameter from the callee back to the caller
- *inout mode* information flows through the parameter from the caller to the callee, then back from the callee to the caller

#### **General Semantics**

In most cases, parameter passing occurs through a run-time stack.

A subroutine call generally involves:

• setting up and initializing memory for parameters

- stack-dynamic allocation of local variables
- saving of the execution status of calling program
- transfer of control and arrange for the return

#### and on return:

- in mode and inout mode parameters must have their values returned
- deallocation of stack-dynamic local variables
- restoration of execution status
- return of control to the caller

The *subprogram linkage*, which is the entire call and return process, most often depends upon an *activation record* placed on the program's run-time call stack.

An activation record for simple subprograms consists of three parts:

- space for local variables
- space for parameters
- the return address

If we have support for stack dynamic local variables (which is the case for the modern languages that support recursion), we also need a register which will hold a base address (often called a *frame pointer*). The frame pointer is the base to which the offsets of all local variables and parameters are added to compute their actual address.

In these cases, a *dynamic link address*, which points to the start of the activation record of the caller, is part of the activation record so it can be restored on return.

See the text examples (or text's PPT) for a few examples of this.

These are accomplished using a number of methods for parameter passing.

## Call by Value

With *call by value*, the formal parameter is initialized by actual parameter. No changes to the formal parameter in the subprogram should propagate back to the actual parameter in the caller.

It is normally implemented by copying, but can be done by providing a write-protected *access path* to the actual parameter.

• With copying, write protection of the actual parameter is easy – the subprogram has no access to it

- However, copying requires extra space, as there are now 2 copies, and extra time, as the copy must be performed
- With an access path, there is the expense of enforcing write protection and access is slower through indirect references

This is the parameter passing method of choice for most modern languages, including C/C++, C#, Java, Pascal, Ruby, Scheme.

## Call by Reference

With *call by reference*, the formal parameter is a reference to the memory location of the actual parameter.

This is used in Pascal (with the var keyword) and C++ with the & operator.

### See Example:

```
/home/cs433/examples/callbyref/callbyref.cpp
```

This is efficient, eliminating the copy and extra storage needed for call by value, but access is slower because of the indirection.

It also introduces potential side effects and aliases.

C appears to have a call by reference, but it is really a call by value where the values are pointers.

#### **See Example:**

```
/home/cs433/examples/callbyref/cpointers.c
```

All object parameters in Java are passed by reference.

## Call by Result

With *call by result*, no information is initially transmitted to the subprogram through the parameter. The formal parameter acts like a local variable in the subprogram, then its final value is sent back to the actual parameter (by copying).

A few problems that can arise:

• If we have

```
f(x, x);
```

which formal parameter from inside f will be copied back to x last?

• If we have

```
f(a[i], i);
```

do we use the original i to find the appropriate array entry to copy back to, or the potentially-modified i?

Both C# and Ada provide call by result by specifying the out keyword to a parameter.

## Call by Value-Result

A parameter passed by value-result is a combination of call by value in that the formal parameter is initialized using the actual parameter's value, and call by result in that the formal parameter's final value is copied back to the actual parameter at the end of the subprogram.

This differs from call by reference in that the formal parameters have local storage during the execution of the subprogram.

Ada supports this by using both the in and out keywords.

## Call by Name

With *call by name* parameters, parameters are passed by a textual substitution. However, it is difficult to implement and is not used by any major language.

The idea is sometimes used at compile time, for example in C, we can use the #define mechanism to define macros that act like call by name.

ALGOL 60 did implement call by name. This allowed for a programming technique called *Jensen's Device*.

```
On the web: Wikipedia article "Jensen's Device" at http://en.wikipedia.org/wiki/Jensen's_device
```

## **Implementing Parameter-Passing**

In most languages parameter communication takes place thru the run-time stack

Pass-by-reference are the simplest to implement; only an address is placed in the stack

## **Overloaded Subprograms**

An *overloaded subprogram* is one that has the same name as another subprogram in the same referencing environment.

This is included in languages including Ada, Java, C++, and C#. The resolution of which should be used for a specific call is based on which definition's protocol matches the call.

### See Example:

/home/cs433/examples/overload

## **Indirect Subprogram Calls**

Sometimes, we do not know until runtime which subprogram will need to be called for a particular run of a program.

In C and C++, this is accomplished through function pointers. Examples where this is used include

• *callback functions*, which are functions passed as parameters to a function that are to be called by that function to perform part of their task

```
On the web: "Callback" on Wikipedia at http://en.wikipedia.org/wiki/Callback_(computer_programming)
```

• the function to call upon creation of a new thread (as in POSIX threads)

### **See Example:**

/home/cs433/examples/pthreadhello

# **Generic Subprograms**

A *generic* or *polymorphic subprogram* takes parameters of different types on different activations.

We saw exampels of overloaded subprograms, which provide ad hoc polymorphism.

With *subtype polymorphism*, a parameter of type T can access any object of type T or any type derived from T (in object-oriented programming languages).

We will primarily consider *parametric polymorphism*, where a subprogram can take a *type parameter*.

The text described generic subprograms in C++, which uses the template keyword:

```
template <class Type>
  Type max(Type first, Type second) {
    return first > second ? first : second;
}
```

The function max can then be called with any datatype for its parameters, and it will return the appropriate type. We can try it:

### **See Example:**

/home/cs433/examples/cppgeneric

Notice that in C++, the Type can be either a primitive type or a class.

In Java, where generic have been supported since version 5.0, type parameters must be classes. With *autoboxing* and *autounboxing*, where needed conversions are automatically made between the primitive types (*e.g.*, int, double, *etc.*) and their Object containers (*e.g.*, Integer, Double, *etc.*), this is less of a restriction than it may at first seem.

Some examples:

### See Example:

/home/cs433/examples/javageneric

This example also includes generic classes in addition to generic methods. Worth a look now, even though it's not part of the subprogram topic.